

Safe, Efficient and Autonomous: Multimodal Library of European Shortsea and inland (waterway) Solutions

Integrating automation into waterborne logistics

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ALICE WEBINAR: AUTONOMOUS INLAND WATERWAY VESSELS: MARKET READY OR ARE THERE STILL LINKS MISSING?

VIRTUAL – 23 JUNE 2026



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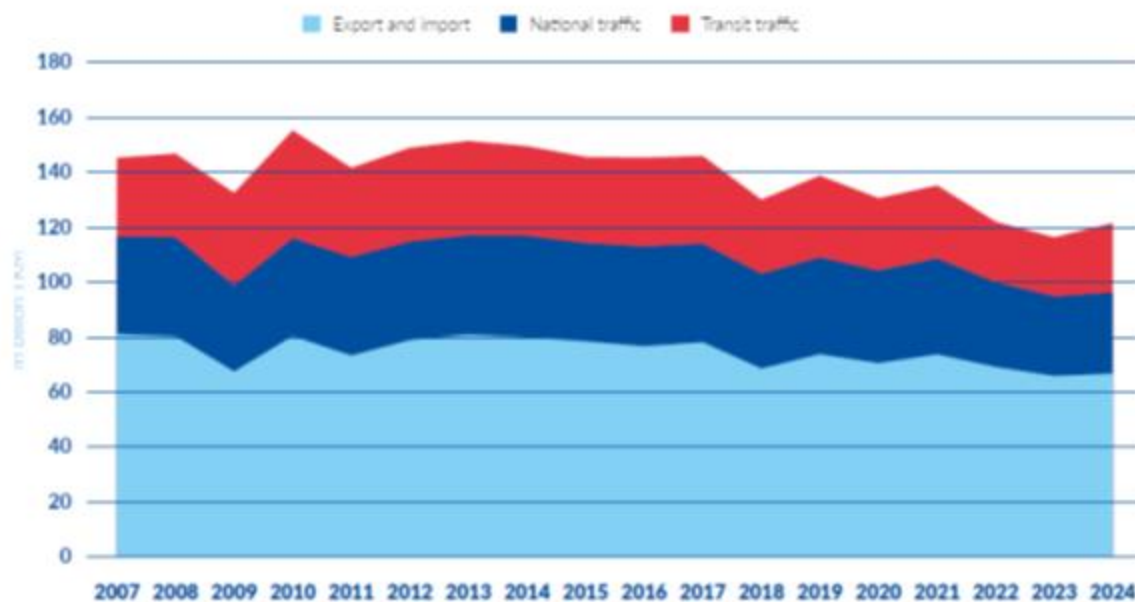
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SEAMLESS

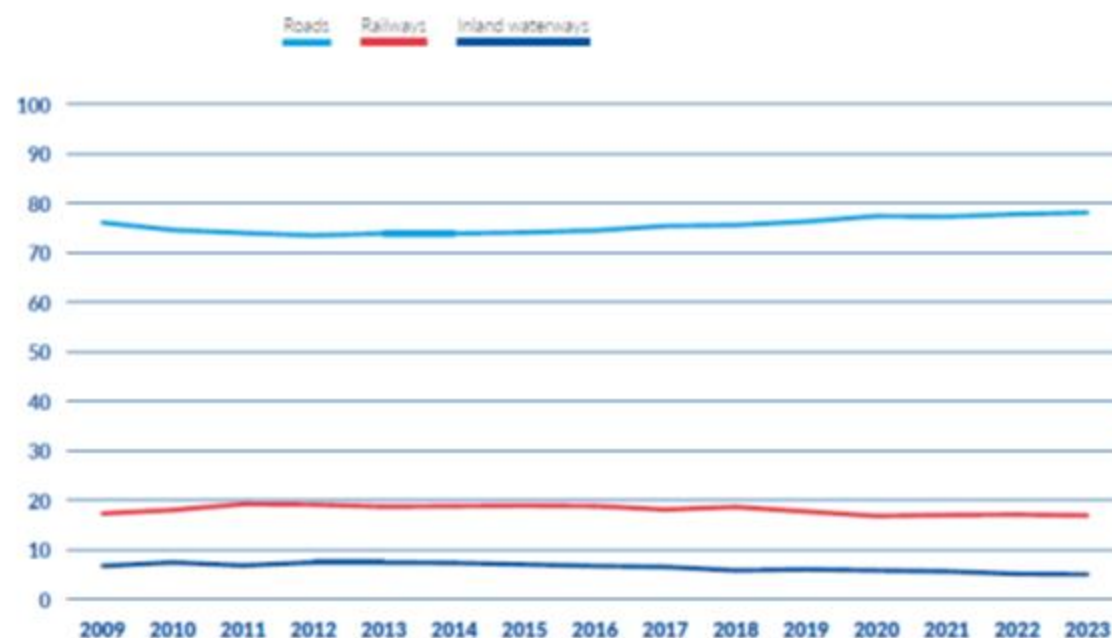
European IWT activity

Annual IWT performance in the EU



Source: CCNR, eurostat

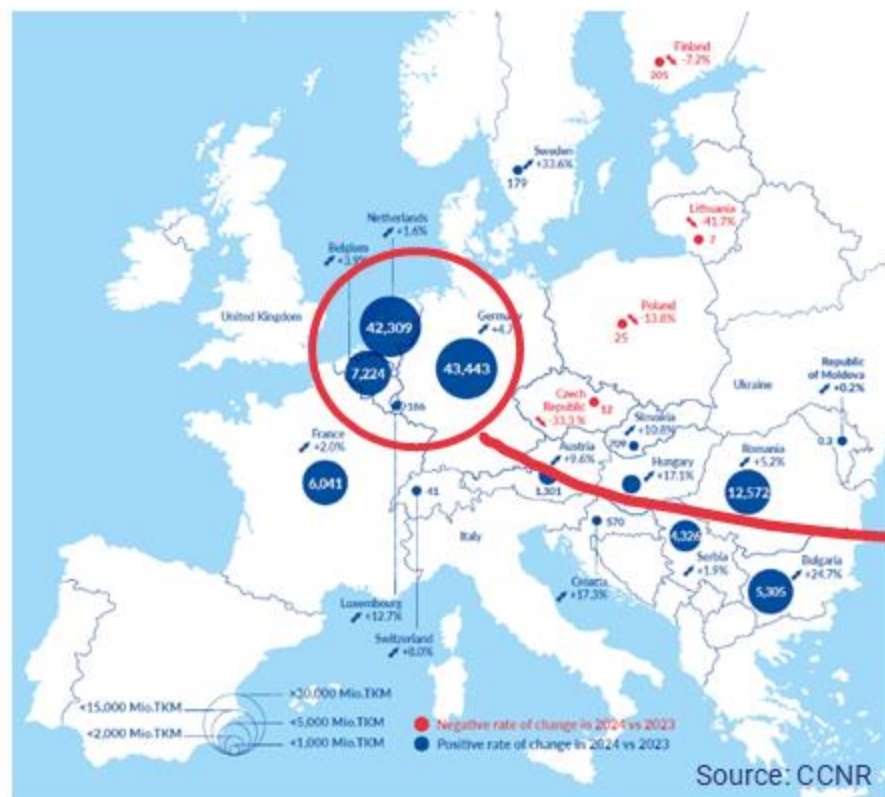
Modal split share of IWT in the EU



Source: CCNR, eurostat



European IWT activity

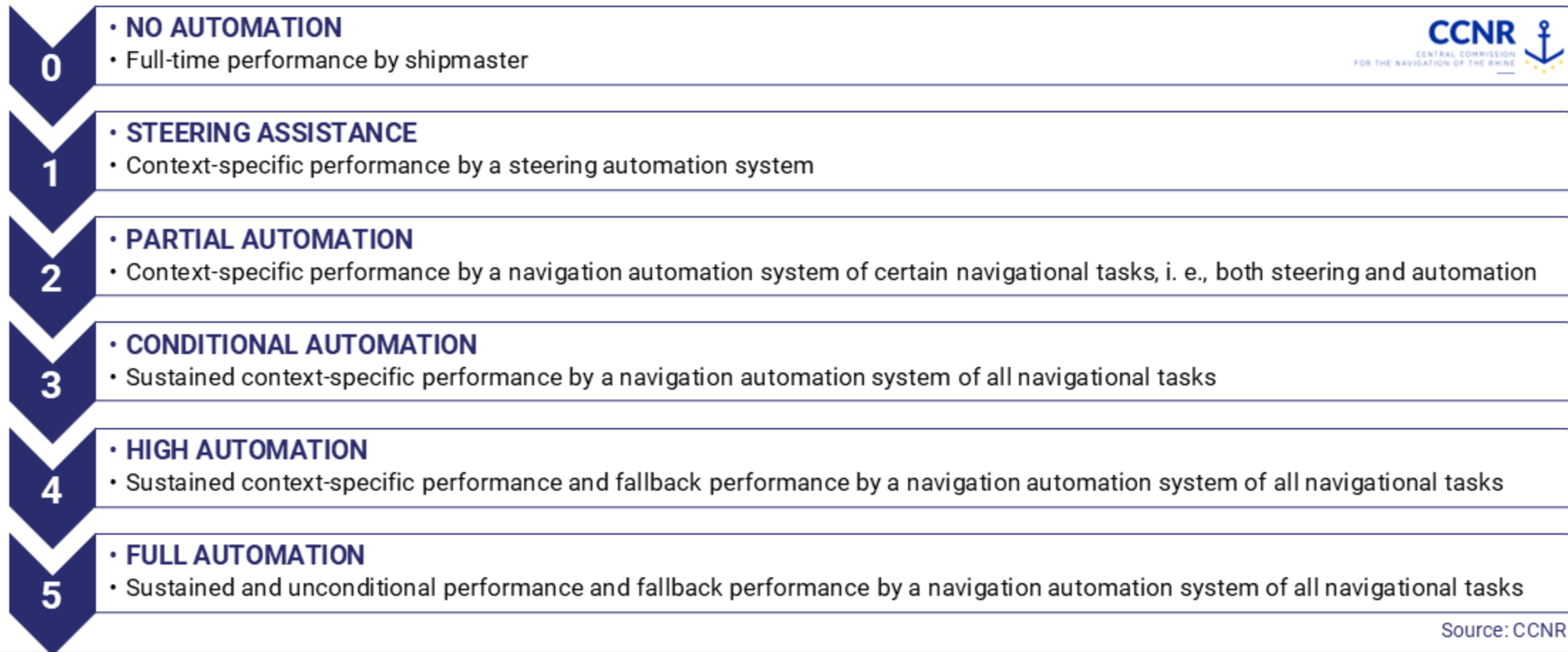


ARA seaports and the hinterland connection on the Rhine-Alpine Corridor, esp. via Duisburg, form the **epicentre of European IWT activity.**

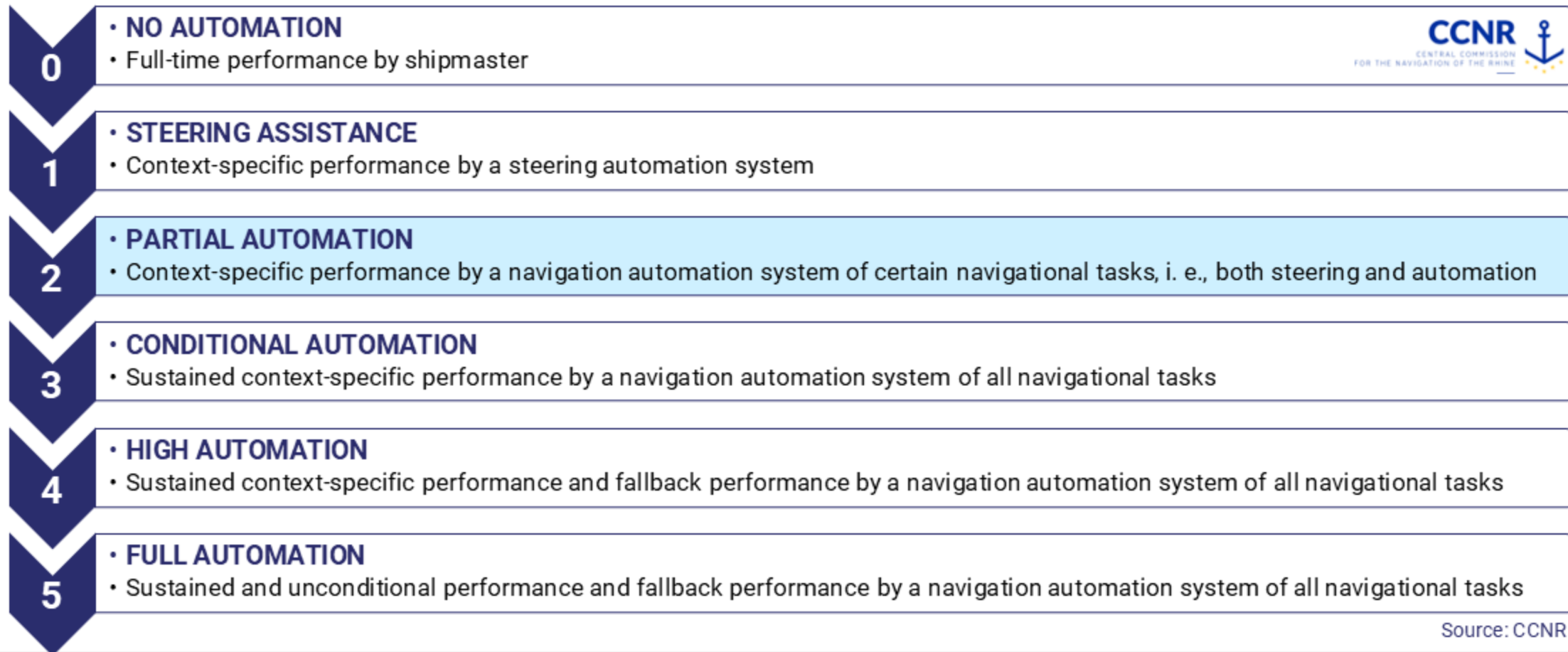
Automation in IWT is coming



Automation in IWT is coming



Automation in IWT is coming





So, what is SEAMLESS about then?



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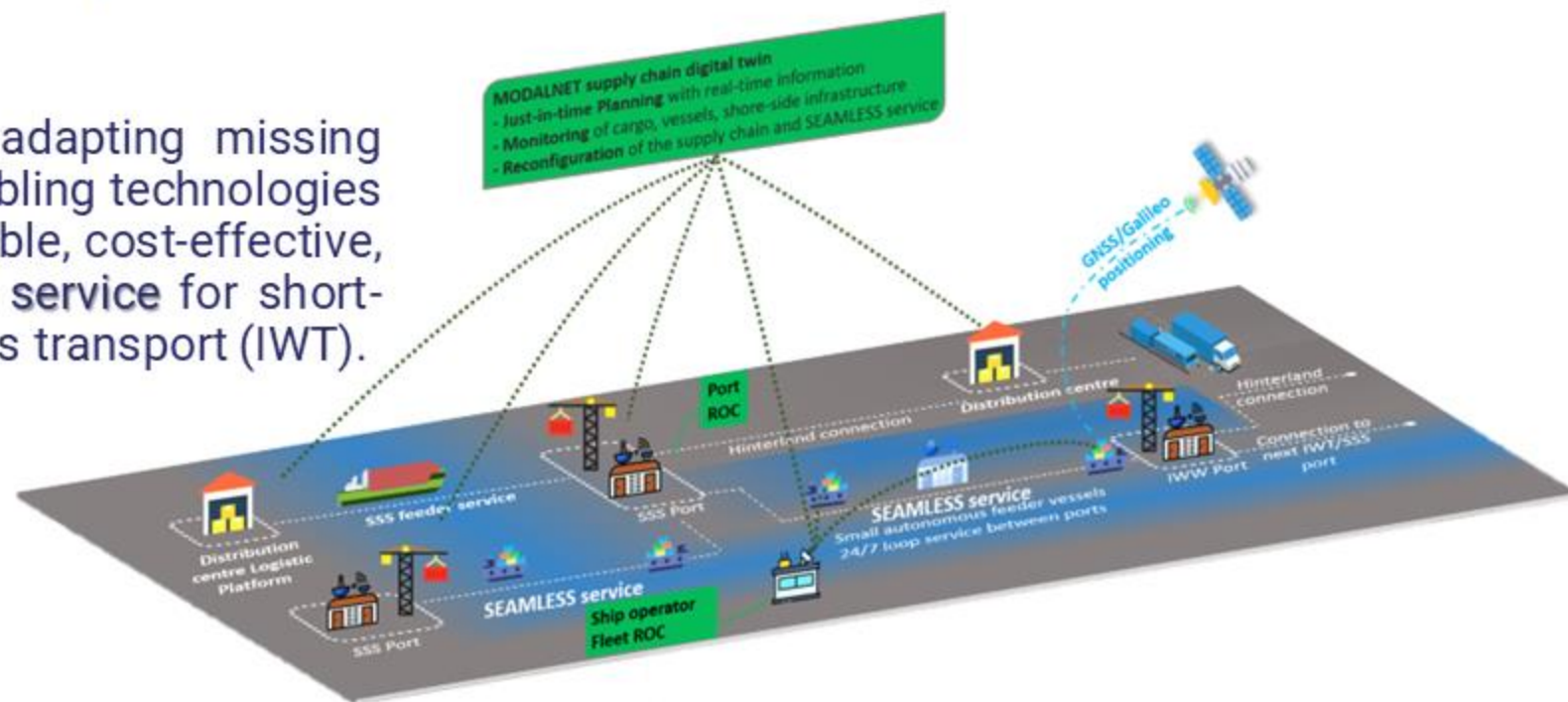
SEAMLESS Transport Service

SEAMLESS aims at developing and adapting missing technology building blocks and key enabling technologies into a fully automated, economically viable, cost-effective, and resilient **waterborne freight feeder service** for short-sea shipping (SSS) and inland waterways transport (IWT).

The SEAMLESS **consortium** comprises of a total of 25 organizations from twelve European countries.

The SEAMLESS **concept** includes

- three Building Blocks
- two Demonstrations
- six Use Cases



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SEAMLESS Use Cases

All SEAMLESS building blocks and enablers will be verified and validated through the **SEAMLESS Use Cases**, which are divided into:

- two **Demonstration** Use Cases (DUCs), one in SSS and another one in IWT, and
 - six **Transferability** Use Cases (TUCs) across the continent.
- The project's technological Building Blocks (BB) will be developed to serve and accommodate the needs of the two DUCs and thus prove the feasibility of the SEAMLESS service
- The TUCs will be examined and evaluated on a higher, conceptual level to determine the transferability potential of the project's BB
- **Having the word “Demonstration” before the first two Use Cases, does not necessarily force us to conduct the actual BB demonstrations to one coherent route****



Integrating automation into waterborne logistics

Automated waterborne seaport hinterland transport





Integrated multimodal transport planning

Automated stowage planning

Interaction with terminals

Remote-controlled navigation

Battery-fuelled propulsion

Automated port calls
Automated mooring

Vision:
„Automated
waterborne
seaport hinterland
transport“

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SEAMLESS Project

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